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“Relative Pay for Non-Relative Performance: Keeping up with the Joneses with Optimal Contracts”

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Relative Pay for Non-Relative Performance:
Keeping up with the Joneses with Optimal Contracts†

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ABSTRACT. We consider multi-agent contracting when agents have “keeping up with the Joneses” (KUJ) preferences. Although contracts appear inefficient, as performance seems inadequately benchmarked, when a single principal can commit to a public contract, the optimal contract hedges agents’ relative wage risk without sacrificing efficiency. With multiple principals, or a principal that is unable to commit, a “rat race” emerges in which agents are more productive, but wages increase even more, reducing profits and undermining efficiency. Renegotiation reduces or enhances efficiency depending on whether KUJ effects are weak or strong. Public disclosure of contracts across firms can cause output to collapse.

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1. Introduction

Optimal contracting and incentive theory has provided powerful insight into the optimal design of compensation contracts. Chief among them, for instance, is the idea that contracts should provide higher compensation when output suggests that the agent was more likely to have engaged in desired behavior. In particular, Holmstrom’s (1992) Informativeness Principle states that any measure of performance that reveals information about the agent’s effort should be included in the compensation contract. A prime example is the use of Relative Performance Evaluation (RPE), in which the agent’s performance is measured relative to an average of her peers in order to filter out common sources of noise. In other words, optimal contracts should not “pay for luck” due to aggregate shocks, but only pay for indicators of individual performance.

The benefit of RPE is that it allows compensation to remain sensitive to the components of output that the agent controls, while reducing exposure to aggregate fluctuations which he cannot control. Despite this clear benefit, in practice it is observed much less frequently than theory would predict. In this paper we explore a possible explanation for lack of RPE in practice: that in addition to their absolute wage, agent’s care about their wage relative to the wages of their peers. When agents have a “keeping up with the Joneses” (KUJ) component to their preferences, relative performance evaluation increases the agent’s perceived risk. We derive optimal contracts in this context and show that the sensitivity of pay to aggregate performance benchmarks will depart dramatically from the predictions of RPE, but this departure need not entail a loss of efficiency.

Our model includes many agents who take hidden effort to produce output that is subject to both common and idiosyncratic shocks. Agents receive a compensation contract which specifies their wage as a function of their own output as well as the aggregate (or average) output of others. Agents are risk averse and have preferences that are increasing in both their own wage as well as the difference between their own wage and the average wage of others. The relative sensitivity to absolute versus relative wages determines the strength of the KUJ effect in our model.

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1 For empirical evidence of “pay for luck” in the context of CEO compensation, see e.g. Murphy (1985), Coughlan and Schmidt (1985), Antle and Smith (1986), Gibbons and Murphy (1990), Janakiraman, Lambert, and Larker (1992), Garen (1994), Aggarwal and Samwick (1999a,b), Murphy (1999), Frydman and Jenter (2010), and Jenter and Kanaan (2014).
We begin in Section 2 by analyzing the RPE benchmark absent any KUJ effect, and show that as expected, compensation in the optimal contract is based on a measure of the agent’s relative performance; that is, compensation is positively related to the agent’s own output and negatively related to the output of others, in relative proportions that depend on the correlation between agents’ output. Indeed, relative performance evaluation implies that the incentive component of wages should be negatively correlated.

We then compare the RPE outcome with that obtained when agents have KUJ preferences and so care about their relative wage. We consider a variety of contracting settings, both within and across firms, and analyze the implications for optimal contract design, wage correlation, profitability, and welfare. We show how externalities across firms create ‘rat race’ effects, that commitment to contract terms does not always improve efficiency, and consider whether public disclosure of wage contracts across firms will help, or undermine, incentives.

We first analyze contracts within a single firm, where all agents are employed by a common principal. There we show that although KUJ preferences significantly alter contract incentives, reversing the standard predictions of the RPE framework, they do not imply a loss of efficiency. Indeed, we show quite generally that with a sufficiently rich contract space, the principal can design wage contracts that effectively neutralize agents’ relative wealth concerns. Doing so, however, leads to lower wage variability within the firm and, if KUJ preferences are sufficiently strong, to positive wage correlation, consistent with empirical evidence on wage compression within firms.\(^2\)

Next we consider a setting with independent principal-agent pairs (for example, boards and CEOs). Again, KUJ preferences lead to convergence of executive compensation across industry peers (in contrast to RPE).\(^3\) In contrast to the prior setting, however, an externality arises as each principal ignores the effect of his agent’s compensation on other firms. A “rat race” ensues, with each firm attempting to raise the power of its own incentives to increase both effort and output. These high-powered incentives impose higher risk on agents, who must then be compensated with higher

\(^2\) For example, Silva (2016) and Gartenburg and Wulf (2016) document wage convergence in multidivisional firms, which is heightened by geographic or social proximity. While inequity aversion is a possible explanation for wage compression (see Englmaier and Wambach (2010) and Koszegi (2014)), our analysis demonstrates that KUJ preferences are sufficient.

\(^3\) Shue (2013) shows similar wage convergence across executives who were former classmates.
average wages. The ultimate effect is an increase in productivity, but a decrease in firm profits (net of wages). We generalize these results to a setting in which independent principals each manage teams of agents (e.g. competitors with multiple workers in similar jobs).

We then explore the role of commitment in contract design by allowing principals to renegotiate privately with individual agents. The principal is tempted to do so since changing the effort of one agent also distorts the performance benchmark in other agents’ contracts, and so can lower the firm’s aggregate wage bill. We show that renegotiation-proof contracts lead to inefficient, excessive effort when KUJ preferences are weak. But when KUJ preferences are strong, renegotiation-proofness dampens the “rat race” externality, lowering effort and raising efficiency in equilibrium.

Finally, we investigate implications of external disclosure requirements, by considering a setting in which independent principals disclose their compensation contracts externally (perhaps as a result of executive compensation disclosure requirements). In that case, because agents care about the performance benchmark their own output will be compared to, their effort decisions become contingent not only on their own contract, but on all observed contracts. We show that in this case, the relative weight that contracts put on aggregate performance increases (compared to a setting with non-disclosure). When KUJ preferences are weak, incentives are inefficiently strong (but not as strong as with non-disclosure). However, when KUJ effects are very strong, public disclosure may cause incentives to collapse as agents end up shirking together.

1.1. Related Literature

There is extensive empirical literature that has for the most part rejected the RPE hypothesis that CEO compensation should depend on relative performance, and so be negatively related to the performance of peers. Examples include: Antle and Smith (1986), Barro and Barro (1990), Jensen and Murphy (1990), Janakiraman, Lambert and Lacker (1992), Hall and Liebman (1998), Joh (1999), Aggarwal and Samwick (1999a,b), and Garvey and Milbourn (2003). Importantly, most of the evidence in these papers documents a positive relation between other firm’s performance and CEO compensation, in direct contrast to the standard RPE prediction. Indeed, Bertrand and Mullainathan (2001) find that CEO pay responds as much to a lucky dollar as a general dollar. And while Janakiraman, Lambert, and Lacker (1992) find some support for a negative sensitivity
to peer performance, they still reject the strong restriction imposed by RPE that the magnitude be such that common shocks are completely filtered out. While a number of hypotheses have been put forth to explain these empirical failures of RPE, KUJ preferences provide a simple intuitive resolution for these findings within the agency model, as these preferences lead to optimal contracts with a reduced magnitude of RPE and, when strong enough, even a positive dependence of pay on external performance measures.

While Keeping/Catching up with the Joneses and habit formation preferences have been used in asset pricing applications starting with Abel (1990), they have received much less attention in explaining behavior in the corporate finance domain. Ederer and Pataconci (2010) introduce status considerations into a tournament setting analyzing implications for the provision of incentives. Goel and Thakor (2010) use envy-based preferences for managers to explain merger waves. Dur and Glazer (2008) consider the optimal contract, with contractible effort, for an employee that is envious of his employer. Goel and Thakor (2005) consider within firm capital allocation decisions of division managers where each manager derives direct utility from wages, and in addition envies both the wages of other managers and their capital allocation as well. Their analysis focuses on induced capital distortions, ignoring the moral hazard and contracting considerations which are the focus of our analysis.

Closer to part of our analysis, Bartling and von Siemens (2010) consider the impact of envy on contracts in a general moral hazard model when a principal hires two agents that are envious of each other. They show that envy can have both cost-increasing and cost-decreasing effects for the principal, and argue that with risk-averse agents and without limited liability envy can only increase the costs of providing incentives. The scope of their analysis is limited by the fact that they do not derive explicit optimal contracts. Itho (2004) derives optimal contracts in a two-agent setting with binary effort and outcomes, and shows that the principal might use relative performance to enhance incentives even if agents’ outputs are uncorrelated. Bartling (2011) analyzes two-agent contracts when agents’ disutility is associated with the ex-ante expected wage inequality; thus, even if one agent earns a higher wage ex-post, his utility is still reduced by the possibility that he could have earned a lower wage. Miglietta (2008) assumes risk aversion both

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4 While closely related, envy refers to a disutility from having a lower wage than one’s peer, whereas keeping up with the Joneses preferences also include a benefit from having a higher wage.
with respect to absolute wage and inequality, and considers also the case with one principal and \( N \) agents. Liu and Sun (2016) consider a similar setting to Miglietta, and focus in systemic risk choices by managers. Fershtman, Hvide, and Weiss (2003) consider a setting with two firms with a single manager in each firm. They assume outputs are uncorrelated, and thus cannot analyze implications of the interaction of RPE and keeping up with the Joneses.

None of the above papers allow for agent heterogeneity, nor do they scale the agents’ outside options to make appropriate welfare comparisons as preferences vary. In contrast, our analysis provides general conditions for efficiency as well as meaningful comparative statics with regard to the strength of relative wealth concerns.

Moreover, we make additional contributions compared to these papers along three important dimensions. First, we investigate when contract disclosure within teams is optimal and compare the associated optimal contracts. Second, we consider a market-wide equilibrium with multiple principals, analyzing the contracting externalities across principals. In doing so, we also analyze how contracts vary as the degree of contract transparency across firms varies. Third, we contrast contracts where the agent’s peer group is solely within the firm to those where peers are employed by other firms.

The KUJ channel for why CEO pay is increasing in peer firm output is distinct yet complementary to other proposed explanations. Aggarwal and Samwick (1999b) abstract from managerial effort choice and show that public contracts could help firms that produce complimentary goods coordinate. Garvey and Milbourn (2003) argue that RPE may be ineffective due to managers’ ability to privately hedge their wage contract. Gopalan, Milbourn and Song (2010) argue that tying CEO compensation to industry performance motivates executives to forecast future growth and optimize the firm’s investment exposure. DeMarzo, Fishman, He, and Wang (2012) show that with long-term contracts, optimal compensation may respond positively to industry shocks in order to reduce future agency frictions. Himmelberg and Hubbard (2000) and Oyer (2004) argue that the positive dependence of compensation on peer performance reflects the fact that the value of executives’ outside opportunities are also market sensitive.

While these explanations are not mutually exclusive, evidence in Duchin, Goldberg, and Sosyura (2014) supports ours as an independent channel. They show that division managers’ compensation
depends positively on other divisions’ performance, and that common membership in social clubs, shared alumni networks and joint board appointments among conglomerate’s division managers amplifies the spillovers of compensation shocks across divisions. Anton, Ederer, Gine, and Schmalz (2016) show that top managers get paid less for own-firm performance and more for rivals’ performance in industries with higher common ownership concentration; common ownership may reduce the desirability of competition within the industry while at the same time making intra-industry wage comparisons more salient.

In addition to highlighting the role that KUJ incentives play in explaining the positive dependence on peer performance, a central contribution of our paper is that we derive novel cross-sectional predictions regarding the degree of RPE. First, we compare settings with a single principal hiring multiple agents to that with multiple principals each hiring an agent. Second, we contrast contracts under different degrees of transparency within and/or across firms. We also produce predictions linking the degree of competition (number of peer firms) and the compensation sensitivity to peer firms’ performance. We also contribute to the literature by showing that some typical comparative statics in the contracting environment are overturned when agents have relative wealth concerns. For example, the prediction linking higher output volatility with less relative performance evaluation, a prediction rejected in Aggarwal and Samwick (1999a), is reversed when keeping up with the Joneses incentives are significant.

2. Basic Model

We consider a setting with $n+1$ total agents. We make the standard assumption that the utility of each agent $i$ is increasing in his own wage, $w_i$, and decreasing in his effort, $a_i$. We depart from the usual principal-agent framework, however, by assuming that agents care about their wage relative to that of their peers. In particular, to capture this effect, we assume the utility of agent $i$ decreases with the average wage of his peers, denoted by

$$w_{i,j} \equiv \frac{1}{n} \sum_{j \neq i} w_j.$$  

(1)

For tractability and to avoid wealth effects, we assume agents have CARA utility and denominate disutility in units of consumption. Specifically, let $u(c) = -e^{-\lambda c}$ and define the agent’s utility as
\[ U(w_i, w_{-i}, a_i) \equiv u \left( \frac{w_i - \delta w_{-i}}{1 - \delta} - \psi(a_i) \right). \] (2)

Here \( \psi \) is the disutility of effort and \( \delta < 1 \) captures the strength of the relative wealth effect. We interpret \( \frac{w_i - \delta w_{-i}}{1 - \delta} \) as the agent’s “relative wage.” This formulation is equivalent to specifying the agent’s effective wage as

\[ w_i + \hat{\delta}(w_i - w_{-i}), \] (3)

with \( \hat{\delta} = \delta / (1 - \delta) \).\(^5\) An important feature of our specification in (2) or (3) is that the KUJ parameter \( \delta \) has no effect if agents are paid the same wage. Thus, if the agent’s actions were observable and could be contracted upon, so that there were no incentive problem, KUJ preferences would have no consequence for wages or efficiency.\(^6\) On the other hand, as (3) makes clear, when wage variation is necessary for incentive provision, agents with KUJ preferences experience additional disutility associated with the risk of the wage differential with their peers.

We assume a quadratic disutility of effort with \( \psi(a) = a^2 / (2k) \), so that the parameter \( k > 0 \) indexes the private cost associated with effort. The production technology has additive shocks, so that the output \( q_i \) of agent \( i \) is equal to a constant plus effort plus noise:\(^7\)

\[ q_i = q_0 + a_i + \epsilon_i. \] (4)

The random shocks \( \epsilon_i \) are joint normal with mean zero and variance \( \sigma_i^2 \), and have a pairwise correlation of \( \rho \in [0,1) \).\(^8\) Adopting the same notation as we did with wages, we write \( q_{-i} \) to denote the average output of the agent’s peers, \( \epsilon_{-i} \) to denote their average shock, etc.

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\(^5\) What is critical in both cases is that, to allow for meaningful comparative statics, we have normalized the relative wage so that the importance of the wage component of consumption compared with the effort cost remains constant as we consider alternative values for \( \delta \). Also, while it is not our main focus, we can allow \( \delta < 0 \) to consider altruistic preferences.

\(^6\) For simplicity we are assuming all agents are ex ante identical. If agents differed, so that even absent incentive issues some agents would earn more than others, peer comparisons could be appropriately normalized.

\(^7\) We can interpret the constant \( q_0 \) as corresponding to output that the agent generates which can be easily monitored and so not subject to an agency problem.

\(^8\) Equivalently, we can write the shocks as \( \epsilon_i = \sigma_i \left[ \sqrt{1 - \rho} \eta_i + \sqrt{\rho} \eta_{-i} \right] \), with \( \eta \) independent standard normal.
Note that in this setting, the first-best effort level maximizes \( a_i - \psi(a_i) \) and thus \( a_i = k \). However, effort choices are hidden and subject to moral hazard. Appropriate compensation contracts are needed to motivate the agent. We restrict attention to linear compensation contracts of the form:

\[
w_i = m_i + x_i q_i + y_i \sum_{j \neq i} q_j = m_i + x_i q_i + ny_i q_{-i}
\]

where \( m_i \) is a constant, \( x_i \) is the sensitivity of the agent’s wage to his own output, and \( y_i \) is the sensitivity of his wage to the aggregate output of his peers. Equivalently, \( ny_i \) is the sensitivity to the average output of other agents.

### 2.1. Relative Performance Evaluation

Before we begin, it is useful to consider the role of relative performance evaluation (RPE) in this context. When the correlation \( \rho \) between the agents’ shocks is positive, there is a common component to output, and thus the output of other agents will be informative with regard to agent \( i \)’s shock. In particular, given the average shock \( \epsilon_{-i} \) of the agent’s peers, we have

\[
E[\epsilon_i \mid \epsilon_{-i}] = \frac{np}{1 - \rho + np} \epsilon_{-i}.
\]

Therefore, in a standard moral hazard setting ignoring relative wealth concerns, the optimal signal (up to a constant) upon which to base the agent’s compensation is

\[
q_i = \theta_{n,\rho} q_{-i},
\]

where we define the RPE benchmark

\[
\theta_{n,\rho} \equiv \frac{np}{1 - \rho + np}.
\]

This signal minimizes the residual risk imposed upon the agent, which is given by

\[
Var(q_i - \theta_{n,\rho} q_{-i}) = \sigma_{n,\rho}^2 \equiv \frac{1 + np}{1 - \rho + np} (1 - \rho)\sigma^2 - (1 - \rho \theta_{n,\rho})\sigma^2. \tag{9}
\]

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9 Goukasian and Wan (2010) demonstrate optimality of linear contracts in this setting in a continuous time context as in Holmstrom and Milgrom (1987). While there is a typographical error in some of their reported results, similar findings apply here, and so under their assumptions our use of linear contracts is without loss of generality.
Note that when $\rho > 0$ and $n$ becomes large, $\theta_{n,\rho} \to 1$ and $\sigma^2_{n,\rho} \to (1-\rho)\sigma^2$, in which case the common risk factor is perfectly filtered out.

Thus, with the contracts in (5), the standard RPE outcome would predict

$$\frac{ny_i}{x_i} = -\theta_{n,\rho}$$

These results form the basis for standard tests of RPE in the empirical literature, which generally conclude that compensation tends to be much less sensitive to peer performance than is predicted by an optimal contracting framework, and indeed often has the opposite sign – pay is positively related to aggregate performance. One of the key goals of our paper is to understand how “pay for luck” can emerge when agents have relative wealth concerns, and how it may effect productivity and profits.

2.2. Effort and Payoffs

Because effort is hidden and independently chosen, each agent will chose his own effort taking as given his own wage contract as well as the wage contracts and effort choices of others. Define

$$c_i = \frac{w_i - \delta w_{-i} - \psi(a_i)}{1-\delta}$$

(11)

to be the agent’s “adjusted consumption.” Then as in the standard principal agent model, the agent’s own effort affects his utility directly via the disutility of effort and the sensitivity of his wage to his own output. Relative wealth concerns add yet a third channel, however, as illustrated in Figure 1: By raising aggregate output, the agent’s own effort affects the benchmark, and thus the wage, of his peers, which ultimately determines the agent’s perception of his own wage.
The agent’s optimal effort choice will depend on the magnitude of each of these channels, as shown in the following lemma.

**Lemma 1.** Given wage contracts \((m, x, y)\), agent \(i\) chooses effort \(a_i = k\alpha_i\) where

\[
\alpha_i = \frac{x_i - \delta y_{-i}}{1-\delta}
\]  
(12)

is the sensitivity of the agent’s relative wage to his own effort. Effort is below first best if \(\alpha_i < 1\).

**Proof:** See Appendix.

Again, because of the agent’s relative wealth concerns, his own effort will depend on the sensitivity of other agents’ wages to his realized output. If \(y_{-i} < 0\), so that agents are penalized if others perform well, then relative wealth concerns will strengthen the agent’s overall incentives.

To evaluate payoffs, note that with normally distributed consumption and CARA utility agents will have mean-variance preferences. That is, given consumption \(c \sim N(\mu, \sigma^2)\), we can evaluate the agent’s utility in terms of the corresponding certainty equivalent consumption level

\[
u^{-1}(E[u(c)]) = \mu - \lambda \sigma^2.
\]

In general, each agent’s payoff will depend upon all other contracts, as these will determine the distribution of the average peer wage. For ex ante identical agents, we expect that equilibrium wage contracts, and thus actions, will be symmetric. That said, equilibrium incentives may depend upon the payoffs that would be obtained were the agent to receive a different contract. As a result,
it is useful to evaluate the payoff for agent \( i \) when all other agents have an identical contract (and choose the same action) but this contract may differ from that of agent \( i \). Specifically, suppose
\[
(m_j, x_j, y_j, a_j) = (m_{-i}, x_{-i}, y_{-i}, a_{-i}) \text{ for all } j \neq i.
\]
Then we have the following characterization.

**Lemma 2.** Suppose agents \( j \neq i \) have symmetric contracts. Then expected wages are given by
\[
E[w_i] = m_i + x_i a_i + y_i n a_j
\]
\[
E[w_{-j}] = E[w_j] = m_j + x_j a_j + y_j (a_i + (n-1)a_j).
\]

Letting \( \alpha_i \equiv \frac{x_i - \delta y_j}{1-\delta} \) be the agent’s total exposure to his own output and \( \beta_i \equiv \frac{n y_i - \delta x_j - (n-1)\delta y_j}{1-\delta} \) be the agent’s total exposure to the output of others, agent \( i \)’s adjusted consumption \( c_i \) has mean and variance
\[
E[c_i] = \frac{m_i - \delta m_j}{1-\delta} + \alpha_i a_i + \beta_j a_j - \psi(a_i)
\]
\[
Var(c_i) = \left[ \left( \alpha_i^2 + \frac{1}{n} \beta_i^2 \right) (1-\rho) + (\alpha_i + \beta_i)^2 \rho \right] \sigma_e^2.
\]

**Proof:** See Appendix. ■

The preceding lemma allows us to recast the contracting problem to a choice of the parameters \((\alpha_i, \beta_i)\) which determine the agent’s exposure to his own risk and to the common risk. Because the agent \( i \)’s incentives are determined solely by \( \alpha_i \), it is optimal to choose \( \beta_i \) to minimize the risk of the agent’s adjusted consumption. The following result characterizes the minimum variance contract, and relates it to the standard RPE solution discussed earlier.
**Lemma 3.** Given $\alpha_i$, the variance of the agent’s adjusted consumption $c_i$ is minimized with
\[
\beta_i = -\alpha_i \left(\frac{n \rho}{1 - \rho + n \rho}\right) = -\alpha_i \theta_{n,\rho}.
\] (13)
In that case, $Var(c_i) = \alpha_i^2 \sigma_{n,\rho}^2$.

**Proof:** See Appendix. □

### 3. Single Principal, Public Contracts

We consider first a setting in which there is a single principal committing to a public contract for a set of $n + 1$ agents. Because of the correlation in output, the principal obtains more precise information about each agent’s effort by considering his output relative to that of his peers. At the same time, the principal anticipates the agents’ concerns regarding relative pay, and must consider this effect when determining how best to provide incentives.

#### 3.1. Optimal Contracts

The principal seeks the contract that will maximize the expected aggregate output of the agents net of the wages paid. Agents choose effort based on the contracts’ incentives, and wages must be set to satisfy a participation constraint. Specifically, the timing is as follows:

![Figure 2: Single Principal with Public Contracts](https://example.com/figure2.png)
Thus, the principal solves the following optimization problem:

\[
\max_{(m,x,y,a)} E\left[ \sum_i q_i - w_i \right]
\]

s.t. for all \(i\),

\[
a_i = k \left( \frac{x_i - \delta y_{-i}}{1 - \delta} \right) \quad (IC)
\]

\[
E[c_i] - \lambda \text{Var}(c_i) \geq c_0 \quad (PC)
\]

Because the fixed component of the agent’s wage, \(m_i\), can be reduced so that (PC) always binds, at the solution to the principal’s problem we must have

\[
E[c_i] = E\left[ \frac{w_i - \delta w_{-i}}{1 - \delta} \right] - \psi(a_i) = c_0 + \lambda \text{Var}(c_i).
\]

Next, note that \(\sum_i w_i = \sum_i w_{-i}\), and therefore the expected aggregate wage bill satisfies

\[
E\left[ \sum_i w_i \right] = \sum_i c_0 + \psi(a_i) + \lambda \text{Var}(c_i).
\]

As a result, we can reduce the principal’s problem to

\[
\max_{(x,y,a)} \sum_i a_i - \psi(a_i) - \lambda \text{Var}(c_i) \quad s.t. \quad (IC)
\]

Note that (17) is the same problem faced by a social planner attempting to maximize total welfare, which consists of expected aggregate output net of the costs of effort and risk-bearing.

Given the convexity of both the effort cost and the variance of consumption in the parameters \((x, y, a)\), it is straightforward to show that the solution to (17) will be symmetric, so that the contracts will be identical for each agent. We characterize the optimal contract below.

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10 Note that we have dropped the constant term \(q_0 - c_0\) from the principal’s objective. This baseline level of surplus is relevant if we consider the principal’s participation constraint, which is to earn a non-negative profit. As long as this baseline surplus is nonnegative, the principal participation constraint will not bind in this case (since he can always achieve at least this level by paying a constant wage).
**Proposition I.** Given a single principal who can commit to a public contract, the optimal contract is symmetric with \( \beta = -\alpha \theta_{n,p} \) and

\[
\alpha = \frac{1}{1 + 2\lambda k^{-1}\sigma_{n,p}^2} < 1. \tag{18}
\]

Effort is given by \( a = k\alpha \), and effort, expected wages, and profits are independent of \( \delta \).

The observed contract parameters are

\[
x = \alpha - \delta(\alpha - y) = \alpha \left(1 - \delta \left(\frac{n + \theta_{n,p}}{n + \delta}\right)\right), \quad y = -\alpha \left(\frac{\theta_{n,p} - \delta}{n + \delta}\right). \tag{19}
\]

**Proof:** See Appendix. \( \blacksquare \)

The results of **Proposition I** are striking. In particular, (18) implies that the agent’s effort choice and the optimal sensitivities \((\alpha, \beta)\) are independent of the strength \(\delta\) of his relative wealth concerns. As a result, expected wages and output are independent of \(\delta\) and thus there is no loss (or gain) of efficiency induced by these preferences. Instead, the principal is able to undo the effect of these preferences through the contract itself. But, while the real outcomes are unaffected by the agent’s relative wealth concerns, the form of the optimal contracts and the resulting wages differ substantially, as we analyze next.

### 3.2. Wage Convergence

While expected wages and profits are not impacted by \(\delta\), the contract sensitivities \((x, y)\) are affected due to the implicit hedging of relative wealth effects embedded in the optimal contract. As relative wealth concerns increase, optimal contracts put more weight on the aggregate benchmark and less weight on the agent’s own performance.

**Corollary I.A** For \( \rho \in (0,1) \), as \( \delta \) increase from 0 to 1,

- \( x \) decreases from \( \alpha \) to \( \alpha(1 - \theta_{n,p})/(n+1) \),
- \( ny \) increases from \( -\alpha\theta_{n,p} < 0 \) to \( n\alpha(1 - \theta_{n,p})/(n+1) > 0 \),
- The relative sensitivity \( y/x \) increases from \( -\theta_{n,p}/n \) to 1.
**Proof:** Immediate from Proposition I.

The above results have important implications for empirical tests of RPE in the presence of relative wealth concerns. Absent these concerns, optimal signal extraction suggests that the agent’s sensitivity to peer performance relative to his own should equal $-\theta_{n,p}$. With relative wealth concerns, the relative sensitivity to peer performance increases with $\delta$. For $\delta > \theta_{n,p}$, the agent’s wage will be increasing with the performance of his peers, as shown in Figure 3. Indeed, for $\delta$ close to 1, the relative sensitivity approaches 1 and thus the agent’s wage will become proportional to aggregate output.

![Relative Contract Sensitivity for Different Degrees of Relative Wealth Concerns](image_url)

**Figure 3:** Relative Contract Sensitivity for Different Degrees of Relative Wealth Concerns

These results have the empirical implication that KUJ-effects will reduce the dispersion of wages, with the wage correlation approaching one when agents care only about their relative wage: $\rho$.

**Corollary I.B** For $\rho \in [0,1)$, as $\delta$ increase from 0 to 1,

- The volatility of each individual’s wage $w_i$ declines.

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11 Englmaier and Wambach (2010) demonstrates that wage compression results if agents are inequity averse, and thus suffer a disutility if their payoff exceeds that of others. Here, even though agents gain from being ahead of their peers, it is still optimal to reduce wage variation.
• The volatility of the agent’s relative wage \( w_i - w_j \) declines to zero,

• The pairwise wage correlation is negative when \( \delta = 0 \) and approaches 1 as \( \delta \) increases.

**Proof:** See Appendix. ■

We illustrate this result in Figure 4.

![Figure 4: Wage Volatility Declines and Correlation Increases with Relative Wealth Concerns](image)

Finally, we derive the following explicit comparative statics from our model. An increase in volatility or risk aversion decreases efficiency (as usual), but does not change the contract’s relative sensitivity to own performance versus the benchmark. As in the standard setting, without KUJ preferences, an increase in output correlation leads to increased effort and decreased (more negative) sensitivity to output of others. However, while the weight on own performance increases with correlation in the standard model, it may decrease in the presence of relative wealth concerns. Similarly, while the relative wage sensitivity \( ny/x \) decreases with \( n \) in the standard RPE framework, the reverse may be true here.

**Corollary LC** We have the following comparative statics:

• As volatility \( (\sigma^2) \) or risk version \( (\lambda) \) increase, effort and \( x \) decrease, while \( y / x \) remains constant.
• As correlation $\rho$ increases and aggregate output becomes more informative, effort increases, while $y$ and $y/x$ decrease. Finally, $x$ is decreasing if

$$\delta \geq \frac{n^2 + n}{n^2 + n + k/(2\lambda)}$$

increasing when $\delta = 0$, and otherwise is u-shaped.

• As the number of agents $n$ increases (which also increase the informativeness of aggregate output), if $\rho = 0$, then $ny/x$ is increasing (or constant if $\delta = 0$). If

$$\rho > \frac{\delta^2}{\delta + 2(1-\delta^2)}$$

then $ny/x$ is decreasing with $n$. Otherwise, it is tent-shaped.\(^2\)

Effort increases with $n$ unless $\delta = \rho = 0$, in which case it is constant.

**Proof:** See Appendix. □

### 3.3. Heterogeneous Agents

**Proposition I** and the results highlighted above provide an important “irrelevance” benchmark for contractual settings with KUJ-type preferences. Indeed, our basic efficiency result is actually far more general than our specific setting, as the following result reveals:

**Proposition II.** Consider any utility functions $u_i$, distribution of shocks $\epsilon_i$, effort costs $\Psi_i$, and let the wage for each agent $i$ be an arbitrary function $w_i$ of the vector of outputs $q$. Then aggregate effort and expected output are independent of $\delta$, and the optimal contract satisfies

$$w_i = (1 - \delta)w_{0i} + \delta w_{-i},$$

where $w_{0i}$ is the optimal contract for $i$ when $\delta = 0$. In the specialized setting of

**Proposition I**, we have

$$x = (1 - \delta)x_0 + \delta y \quad \text{and} \quad ny = (1 - \delta)ny_0 + \delta(x + (n-1)y).$$

where $x_0 = \alpha$ and $y_0 = -\alpha \theta_{n,\rho}/n$ are the optimal contract sensitivities when $\delta = 0$.

---

\(^{12}\) In the special case $\rho = \frac{\delta^2}{\delta + 2(1-\delta^2)} > 0$, then $ny/x$ is constant for $n = 1, 2$ and then decreases.
As **Proposition II** highlights, efficiency follows from two key aspects of our model. First, the space of wage contracts must be sufficiently rich so that (20) is feasible; in our setting with linear contracts, symmetry across agents allows us to write the contract as a function of only the agent’s own output and the aggregate output of others. Second, the impact of relative wage dispersion on utility is linear in consumption; if instead agents were more (or less) risk averse about their relative wage than about their absolute wage, changing \( \delta \) would change their overall risk aversion and therefore necessarily impact efficiency. But with a sufficiently rich contract space, as long as relative wealth concerns do not change effective risk aversion or the relative cost of effort, efficiency is unaffected. What is affected is the form of the optimal contract, with a significant departure away from the standard prediction of relative performance evaluation toward compensation based on aggregate performance.

Another dimension along which agents may differ is the strength \( \delta_i \) of each agent’s relative wealth concerns. As long as \( E[w_{0i}] \) is equal across agents, it is straightforward to generalize (20) to show that the optimal wage contracts satisfy\(^\text{13}\)

\[
 w_i = (1 - \delta_i)w_{0i} + \delta_i w_{-i}.
\]

(22)

A useful special case is when a subset of the agents do not have KUJ-type preferences, while others do, which we evaluate explicitly next.

**Proposition III.** Suppose agents are identical except that some number \( z \leq n \) do not have relative wealth concerns so that for these agents, \( \delta = 0 \). Then the optimal contract for agents with \( \delta = 0 \) is the RPE contract \( (x_0, y_0) \). The optimal contract for agents with \( \delta > 0 \) has sensitivity \( x \) to own output, \( y \) to the output of others agents with positive \( \delta \), and \( \hat{y} \) to the output of agents with \( \delta = 0 \), where

\[
 x = y + \frac{n(1 - \delta)(x_0 - y_0)}{n + \delta}, \quad y = y_0 + \frac{(1 - \delta)n}{n + \delta} \frac{\delta(x_0 - y_0)}{(1 - \delta)n + \delta z}, \quad \hat{y} = y_0 + \frac{\delta(x_0 - y_0)}{(1 - \delta)n + \delta z}.
\]

(23)

Moreover, \( x < x_0 \), \( \hat{y} > y > y_0 \), and \( x, y, \) and \( \hat{y} \) decline with \( z \).

\(^{13}\) More generally, we need that \( E[w_{0i}] \) is uncorrelated with \( \delta_i \) to be sure the expected wage bill is unchanged.
**PROOF:** See Appendix.

**Proposition III** demonstrates that when agents differ in their relative wealth concerns, the optimal sensitivity to output will also vary. In particular, \( \hat{y} > y \) indicates that the wage of agents with \( \delta > 0 \) is more sensitive to the output of agents without relative wealth concerns. The intuition is that because \( x_o > x \), agents without relative wealth concerns have wages that are more sensitive to their own output, and the principal insures agents with \( \delta > 0 \) to remove this relative wage risk.

Perhaps more relevant empirically is the average sensitivity of the agent’s wage to peer performance, defined by

\[
\bar{y} \equiv (n - z) y + z \hat{y}.
\]

(24)

Interestingly, the presence of non-KUJ agents increases the relative sensitivity \( \bar{y} / x \) of agents with relative wealth concerns, thus amplifying the departure from RPE for agents with positive \( \delta \).

**Corollary III.a** Suppose agents are identical except that \( z \leq n \) agents have non-KUJ preferences. Then for the remaining agents, if \( 0 < \delta \leq \left( \frac{n}{n + \theta_{n,p}} \right)^2 \), the optimal contract satisfies:

- \( y / x \) and \( \hat{y} / x \) decline with \( z \),
- The average sensitivity \( \bar{y} / x \) increases with \( z \).

**Proof:** See Appendix.

While both \( y / x \) and \( \hat{y} / x \) decline with the number \( z \) of non-KUJ agents, the composition effect reverses this trend for the average sensitivity \( \bar{y} / x \). Thus, the presence of non-KUJ agents only strengthens the violation of RPE for the remaining agents.

Another possible form of heterogeneity exists if agents care more about their relative wage with respect to some peers rather than others. For example, suppose we can partition the agents into

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\(^{14}\) We must impose an upper bound on \( \delta \) to derive meaningful comparative statics in this case because if \( \delta \) is too close to 1, the insurance effect for KUJ agents becomes so strong that \( x < 0 \) (though the agent still has positive work incentives due to his desire to raise the benchmark for others). The bound given here is sufficient; we derive tight bounds in the proof.
distinct subgroups such that each agent only cares about his relative wage with respect to others in the same group. The principal may still wish to base payments on the output of all agents to filter out common shocks, but only needs to insurance agents for the relative wealth risk within their subgroup. Using the methodology from Proposition II, we have the following result:

**Proposition IV.** Suppose agents care only about their relative wage within their subgroup of size \( \hat{n} + 1 \). Then the optimal contract for these agents has sensitivity \( x \) to own output, \( y \) to the output of others within their subgroup, and \( \hat{y} \) to the output of agents outside their subgroup, where

\[
x = \alpha \left( 1 - \delta \left( \frac{\hat{n} + \frac{\hat{n}}{n} \hat{\theta}_{n,\rho}}{\hat{n} + \delta} \right) \right), \quad y = -\alpha \left( \frac{\frac{\hat{n}}{n} \hat{\theta}_{n,\rho} - \delta}{\hat{n} + \delta} \right), \quad \hat{y} = -\alpha \left( \frac{\hat{\theta}_{n,\rho}}{n} \right).
\]

(25)

Moreover, \( \frac{\hat{n}}{n} \hat{\theta}_{n,\rho} = \hat{\theta}_{n,\hat{\rho}} \) where \( \hat{\rho} = \frac{\rho}{1 + (n - \hat{n})\rho} \). The relative sensitivity \( y / x \) increases as \( \hat{n} \) declines or \( n \) increases.

**Proof:** See Appendix. ■

Therefore, when agents care only about a subgroup of their peers, the optimal contract will show even larger deviations from RPE on this subgroup.

4. **Multiple Principals**

We now consider a setting in which there are many independent principals. For example, suppose each principal manages a single agent, but the agent’s performance can be benchmarked against the performance of agents at other firms. Such a setting could correspond, for example, to the case of CEOs: CEO compensation is set independently by firm boards, but because firms may be affected by common shocks, performance measures are often benchmarked to industry averages. At the same time, CEOs may evaluate their wage relative to those of their peers.\(^{15}\)

With multiple principals, an externality arises in that each principal does not account for the negative impact of the wage he pays on the utility of agents at other firms. The result is a “rat race” equilibrium in which effort and productivity are higher than in the single principal case, and

\(^{15}\) Alternatively, our setting with individual principals might even apply within a firm, if agents are overseen by different managers and these managers set contracts in an uncoordinated fashion.
may even exceed the first best. But this increase in output comes at the expense of excessive wages, causing profits and efficiency to decline. Despite this loss of efficiency, the relative sensitivity of contracts to own versus others’ output (and the corresponding violation of RPE) is, surprisingly, identical to Section 3.

In Section 4.2, we generalize our results to principals who manage multiple agents, and show that the effects outlined above are dampened as the principal internalizes the impact of higher wages throughout the organization.

4.1. Single-Agent Contracts

Consider first the setting in which each principal contracts privately and independently with a single agent. We assume the following timing:

![Figure 5: Many Independent Principals Setting Contracts Privately](image)

When individual contracts are private, principal-agent pair $i$ will negotiate anticipating and taking as given the equilibrium contracts and action choices of others. Of course, in equilibrium these expectations should be correct. Given $(m_{-i}, x_{-i}, y_{-i}, a_{-i})$, the optimal contract for agent $i$ solves

$$\max_{(m_i, x_i, y_i, a_i)} E[q_i - w_i]$$

s.t. $a_i = k \left( \frac{x_i - \delta y_{-i}}{1-\delta} \right)$ (IC$_i$)

$$E[c_i] - \lambda Var(c_i) \geq c_0 \quad (PC_i)$$ (26)

As in the prior setting, because the fixed component of the agent’s wage, $m_i$, can be reduced so that (PC$_i$) always binds, (15) holds, which implies

$$E[w_i] = \delta E[w_{-i}] + (1-\delta)[c_0 + \psi(a_i) + \lambda Var(c_i)]$$ (27)

As a result, we can reduce the principal’s problem to
Comparing (28) with the optimization for a single principal in (17), we can see that they coincide when $\delta = 0$. When $\delta > 0$, independent principals do not account for the negative externality of a higher wage for their own agent on the utility of other agents. This effect manifests itself in (28) as a lower weight on the cost of inducing effort. In addition, each principal benefits from inducing actions that, by manipulating the performance benchmark, reduce the expected wage of other agents and thereby raises the utility of their own agent.

Of course, because agents are not fooled in equilibrium, these manipulations will not be effective – if agents anticipate that other agents will work harder and earn more, their wage will also need to be higher, and all wages will rise to the detriment of total overall welfare. In other words, because each agent’s wage imposes a negative externality on others, an inefficiency arises when contracts are set independently.

We derive the optimal solution below, where we use the superscripts “$S$” and “$M$” to denote the corresponding solutions from the single and multiple principal cases, respectively.

**PROPOSITION V.** Given independent principal-agent pairs who contract privately, the equilibrium contract is symmetric and has

$$
(\alpha^m, \beta^m, x^m, y^m, a^m) = \frac{1}{1 - \delta(1 - y')} (\alpha', \beta', x', y', a').
$$

Equilibrium effort is above the single principal case when $\delta > 0$, and increases with $\delta$. Welfare is decreasing in $\delta$.

**PROOF:** See Appendix. ■

As **PROPOSITION V** demonstrates, when contracts are determined independently, both effort and incentives will be distorted upward. The representation of the equilibrium contract in (29) is remarkably simple: The term $\delta(1 - y')$ elegantly captures both the negative externality of the agent’s wage on others (via $\delta$) and the desire to manipulate the benchmark (via $y'$). Note that the two effects work in opposing directions when $\delta$ is high enough so that $y' > 0$, but nevertheless the proposition shows that the delta effect always dominates.
Overall, independent contracting increases incentives and effort, but exposes the agent to increased risk. The higher disutility from risk leads to an overall reduction in welfare. Holding fixed agents’ outside option, this setting would therefore show higher productivity and wages, but lower firm profitability, than the social planner solution in Proposition I. Moreover, these distortions increase with the degree of “keeping up with the Joneses” concerns on the part of agents. At the extreme, when $\delta$ is close to 1, effort will exceed the first best.\(^{16}\) See Figure 6.

\(^{16}\) When $\delta = 1$, effort incentives become $\alpha'' = \alpha' / y = (n+1)/(1-\theta_{n,\rho}) > 1$. 

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16 When $\delta = 1$, effort incentives become $\alpha'' = \alpha' / y = (n+1)/(1-\theta_{n,\rho}) > 1$. 

24
While effort and wages are distorted, however, because both $x$ and $y$ are simply rescaled: the relative sensitivity of the agent’s compensation to own versus others output is unchanged.

**Corollary V.A** The relative sensitivity $y^m / x^m = y^x / x^x$.

**Proof:** Immediate from Proposition V. □

Together, the results of Section 3 together with Proposition V demonstrate the potential separation of efficiency from relative performance evaluation in the presence of relative wealth concerns. In Section 3 we showed that we can observe large deviations from the standard RPE contract while maintaining efficiency, while here we have shown that those same deviations of the contract can be associated with large inefficiency in the outcome.

Finally, we have the following comparative statics results:

**Corollary V.B**

- As volatility $(\sigma^2)$ or risk aversion $(\lambda)$ increases, effort and $x^m$ decrease, while $y^m / x^m$ is unchanged.

- As correlation $\rho$ increases, effort increases, $y^m$ decreases, and $x^m$ initially decreases (if $\delta > 0$) and then increases.

- As $n$ increases, if $\rho = \delta = 0$ effort is constant. If $\rho = 0$ or $\frac{k}{2\lambda} \leq \frac{1-\rho}{\delta}$ effort increases, otherwise, if $\frac{k}{2\lambda} \geq \left(\frac{1-\rho}{\delta}\right) \frac{1-\delta^2(2+\delta)\rho^2}{(2\rho^2-\delta(1-(2-\rho)\rho))}$ effort is tent-shaped (decreases).

**Proof:** See Appendix. □

As shown in the above corollary, in contrast to when there is a single principal, the sensitivity to own performance can be lowest when output correlation is low.
4.2. Multi-Agent Firms

Now suppose each principal manages a group or team of agents who are benchmarked to a broader population. These teams might correspond to workers in similar occupations in separate firms (e.g. textile workers at nearby plants, or executives at competing firms within an industry), or even workers in separate departments within a firm (if their teams are managed independently).

Specifically, we let $n + 1$ be the size of the total population of peers as before, and assume each principal manages a team of $\hat{n} + 1$ agents, with $\hat{n} \in [0, n]$. Note that this setting generalizes the cases we have analyzed this far: When $\hat{n} = n$ we are in the single principal setting of Section 3, whereas the single agent setting of Section 4.1 corresponds to $\hat{n} = 0$.

We assume that each principal proposes contracts to the members of his team independently. Agents know the contracts of other members of their team, but don’t observe (and so must anticipate in equilibrium) the contracts used at different firms. We assume for simplicity that the strength of peer effects is the same both within and across teams (though it would be straightforward to allow for peer effects to be stronger within teams).

When principals set the contracts for their team, the same distortion arises as in Proposition V – each principal ignores the cost of paying higher wages on the utility of outsiders, and moreover perceives a benefit from changing effort in a way that might reduce the expected wage of outsiders. The distortion is mitigated, however, as the fraction of workers who are outsiders diminishes as team size increases.

**Proposition VI.** Suppose each principal contracts with $\hat{n} + 1$ agents. Contracts are public within the team but private across teams. Then the equilibrium contract is symmetric and has

$$(\alpha^\hat{\hat{\delta}}, \beta^\hat{\hat{\delta}}, x^\hat{\hat{\delta}}, y^\hat{\hat{\delta}}, a^\hat{\hat{\delta}}) = \frac{1}{1 - \hat{\delta}(1 - y^\hat{\hat{\delta}})} (\alpha^\hat{\delta}, \beta^\hat{\delta}, x^\hat{\delta}, y^\hat{\delta}, a^\hat{\delta}).$$ \hspace{1cm} (30)

where

$$\hat{\delta} = \frac{n - \hat{n}}{n - \hat{n}\hat{\delta}} \delta \leq \delta.$$

Hence equilibrium effort is increasing with $\hat{\delta}$ and distorted upward as in Proposition V, but to an extent which is decreasing in $\hat{n}$ (and disappears when $\hat{n} = n$).
PROOF: See Appendix. ■

Again, note that (30) nests both of our earlier results. The single principal setting corresponds to $\hat{n} = n$, while many principal setting in PROPOSITION V corresponds to $\hat{n} = 0$.

5. Commitment, Disclosure and Renegotiation

Thus far we have assumed that each principal discloses the incentive contracts used within the firm, and cannot privately alter individual contracts. But suppose individual agents can attempt to renegotiate with the principal, and the principal cannot commit to refrain from such renegotiation. If contract alterations are possible, and can be hidden from other agents within the firm, then in equilibrium we should require that contracts be renegotiation-proof.

If the principal and agent renegotiate privately, they will ignore the impact of their wage choice on the utility of other agents, as well as try to lower the wage of others through the performance benchmark, just as in single agent setting of Section 4.1. Moreover, there is now an added benefit to the principal: lowering the wage of other agents within the same firm contributes directly to the principal’s profits.

But while there is an incentive to renegotiate, the opportunity to do so must hurt the principal ex-ante. In equilibrium, other agents within the firm will anticipate the renegotiated contract and seek commensurate terms. In other words, because the renegotiation-proof contract could always be proposed in an environment with disclosure, allowing hidden renegotiation only constrains the principal.

But while each principal is individually worse off with hidden contracting, the equilibrium consequence of renegotiation is less clear: constraining contracts in this way might reduce some of the inefficiency that arose from independent contracting in Section 4. The following result characterizes the equilibrium outcome when hidden renegotiation cannot be prevented:
**Proposition VII.** Suppose each principal privately contracts with a team of \( \hat{n} + 1 \) agents. Then the renegotiation-proof equilibrium contract is symmetric and has

\[
(\alpha^n, \beta^n, x^n, y^n, a^n) = \frac{1}{1 - \delta(1 - y^s) + \hat{n}y^s} (\alpha^*, \beta^*, x^*, y^*, a^*) .
\]  

Equilibrium effort is above the single principal case when \( \delta > 0 \), and increases with \( \delta \). Effort increases in \( \hat{n} \) if \( \delta < \theta_{n,\rho} \) and decreases in \( \hat{n} \) if \( \delta > \theta_{n,\rho} \). Welfare varies inversely with effort. Finally, in the special case \( \hat{n} = n \), so that there is a single principal who contracts privately with each agent,

\[
\frac{1}{1 - \delta(1 - y^s) + \hat{n}y^s} = \frac{1}{1 - \left( (1 - \alpha^s)\delta + \alpha^s\theta_{n,\rho} \right)} .
\]

**Proof:** See Appendix. ■

Comparing (31) with (30), we note two effects. First, \( \hat{\delta} \) is replaced with \( \delta \) because the principal does not consider the impact of the renegotiation with one agent on the utility of other agents on the team when the renegotiation is hidden. Second, the new term \( \hat{n}y^s \) captures the principal’s gain from manipulating the performance benchmark to lower wages for the rest of the team. In particular, note that the renegotiation-proofness constraint creates a distortion when \( \hat{n} > 0 \) even if \( \delta = 0 \). That is because even without relative wealth concerns, the principal can manipulate the wages of other agents on his team by manipulating the RPE benchmark.

On the other hand, when relative wealth concerns are strong and \( \hat{\delta} > \theta_{n,\rho} \), then \( y^s > 0 \) and each agent’s wages are positively related to the output of others. In that case, renegotiation-proofness implies that productivity will decrease with team size, but efficiency will improve. As a result, with multi-agent firms, lack of commitment and hidden contracting with firms can improve efficiency when relative wealth concerns are strong:

**Proposition VIII.** Suppose each principal manages a team of \( \hat{n} + 1 \) agents, with \( 0 < \hat{n} < n \). Then for \( \delta \) close to zero, public contracting within the team dominates private contracting. However, when \( \delta \) is close to one, private contracting is more efficient.

**Proof:** See Appendix. ■
Another natural comparison is the case of a single principal, who cannot commit, to the case of independent principals each managing a single agent.

**COROLLARY VII.A** If a single principal can privately renegotiate, wages and effort are higher, and profits are lower, than with independent principals if \( \delta < \theta_{n,p} \) so that \( y^s < 0 \).

The converse holds when \( \delta > \theta_{n,p} \) and therefore \( y^s > 0 \).

**PROOF:** Follows immediately from the characterization in **PROPOSITION VII.** ■

### 6. External Disclosure

Until now we have considered only the possibility of disclosure of contracts within a team (i.e. a single principal’s span of control). In this section we consider the case in which contracts are disclosed externally, so that all agents are aware of the contracts held by all others.

Consider the case in which there is an independent principal setting the contract for each agent (i.e. teams are size one, and \( \hat{n} = 0 \) ). Then taking \((m_{-i}, x_{-i}, y_{-i})\) as given, the optimal contract for principal and agent \(i\) solves

\[
\max_{(x_i,y_i,a_i,a_{-i})} \quad a_i - \left( \delta E[w_{-i}] + (1-\delta)[\psi(a_i) + \lambda \text{Var}(c_i)] \right) \quad \text{s.t. (IC)} \tag{32}
\]

The difference between this case and (28) of Section 4 is that principal and agent \(i\) recognize that once their contract is disclosed, other agents will adjust their actions \(a_{-i}\) accordingly. In other words, they will solve for their optimal contract taking into account the (IC) constraint for all agents, not solely that for agent \(i\).

Note that the (IC) constraint for other agents can be written as
\[ a_{i} = k \left( \frac{x_{i} - \delta \left( \frac{m-1}{n}, y_{i} + \frac{1}{n}, y_{i} \right)}{1-\delta} \right). \]  

(33)

Therefore, \( y_{i} \) will affect the actions of other agents, and principal \( i \) will have an incentive to manipulate \( a_{i} \) through this channel. Raising \( y_{i} \) will induce other agents to reduce their effort in order to reduce the benefit to agent \( i \). But when other agents reduce their effort, they will also receive a lower wage (as long as \( x_{i} + (n-1)y_{i} > 0 \)), and this lowers the cost of compensating agent \( i \). As a result, equilibrium contracts will no longer choose \( y_{i} \), or equivalently \( \beta_{i} \), to minimize variance as in Lemma 3, but will instead involve higher \( y \) and lower overall effort. Moreover, the solution will no longer be a simple rescaling of the solution in Proposition I, as we can see in the following result.

**Proposition IX.** Suppose independent principals each manage a single agent, and all contracts are disclosed prior to agents choosing effort. Then the equilibrium contract is symmetric and satisfies:

\[
\frac{y_{md}}{x_{md}} = \frac{y^{*} + B}{x^{*} - (n-1)B}
\]

(34)

and

\[
a_{md} = a_{m} - \frac{\delta^{2} (1-\delta \rho) \left( \frac{\delta}{2\lambda k^{-1}} + \rho(n+\delta)(1-\delta) \right)}{(1-\delta)(W_{1}(W_{1} + W_{2}))},
\]

(35)

where

\[
B = \left( \frac{\delta \sigma_{x}}{n} \right)^{2} \frac{\theta_{n,p} \sigma_{n,p}^{2}}{(n+\delta)(1-\alpha') p} \geq 0,
\]

\[
W_{1} = \left[ n + \left( \frac{1}{\alpha'} - 1 \right)(n+\delta) \right] (1-\delta)(1-\rho + np) + \delta (1-\rho) > 0,
\]

\[
W_{2} = \left( \frac{n-1}{2\lambda k^{-1}} \right). \]

**Proof:** See Appendix. ■
Recent regulation has increased disclosure requirements of CEO compensation.\textsuperscript{17} Comparing the setting with publicly disclosed contracts to the one with undisclosed contracts shows that publicly disclosed contract generally imply higher relative sensitivity compared to when contracts are undisclosed (see (34)). These higher sensitivities imply that with KUJ incentives increasing transparency leads to an increase in expected compensation. Consistent with this prediction, Gipper (2016) shows that the 2006 SEC enhanced disclosure requirements on managerial compensation increased CEOs’ pay. In addition, the U.S Congress Jumpstart Our Business Startups (JOBS) Act of 2012, that rolled back some disclosure requirements for a subset of firms lead to a decline in managers’ compensation.\textsuperscript{18} Furthermore, as the KUJ incentives increase effort at first increases (though to a lesser extent than with undisclosed contracts) but then decreases. With sufficiently high KUJ incentives the equilibrium contract distortions induce an effort level below the effort level with a single principal. The principal’s payoff is also non-monotonic, initially decreasing as effort rises, then increasing as effort becomes closer to second-best, and finally decreasing as effort drops further. Ultimately, if KUJ effects are sufficiently strong, effort collapses as shown in Figure 8. Indeed, there exists a cutoff such that if and only if $\delta$ exceeds the cutoff, then equilibrium profits are lower when contracts are externally disclosed. Thus, external disclosure requirements are unique in creating the possibility that relative wealth concerns may lead to equilibrium effort and productivity below that of the standard contracting environment.

\textsuperscript{17} In December 2006, the Securities and Exchange Commission (SEC) issued new enhanced disclosure requirements on CEO compensation (for details see http://www.sec.gov/rules/final/2006/33-8732a.pdf).
\textsuperscript{18} Further evidence, in other settings, that increased disclosure of executive compensation increases executive pay is provided in Park, Nelson, and Huson (2001), Perry, and Zenner (2001), Schmidt (2012), and Mas (2016).
Conclusion

In this paper we have extended a standard moral hazard optimal contracting framework to a setting in which agents care about both their absolute wage, as well as how their wage compares to that of their peers, both within and across firms. We show that as the strength of this Keeping Up with the Joneses (KUJ) component of preferences increases in importance, optimal contracts deviate from relative performance evaluation and thus exhibit “pay for luck.” In the extreme, agents are paid only on the basis of aggregate output, rather than for their individual performance.
Our analysis centers at providing a broad overall perspective of the implications of KUJ preferences on contracts and efficiency, by analyzing three previously unexplored key contracting dimensions. First, we contrast settings in which a single principal hires multiple agents to those in which multiple principals independently hire one or a team of agents. Second, we consider the role of the principal’s ability or inability to commit to the contract they propose to agents. Third, we shed light on the equilibrium implications of requiring firms to publicly disclose executive compensation contracts.

Surprisingly, despite the fact that contracts may appear to provide suboptimal incentives, we provide general conditions such that when there is a single principal, efficiency is unaffected by KUJ preferences. Rather, optimal contracts hedge the added risk from relative wage concerns, and effort, average wages, and profitability are unaffected. The correlation between wages rises, however, with the degree of relative wage concerns.

When there are multiple principals, contracts display the same relative sensitivity to aggregate versus individual output as with a single principal. But now, contracts fail to account for the externality that an increase in output has on the welfare of other agents. A “rat race” ensues and principals use inefficiently high-powered incentives, and agents work too hard. In equilibrium, they demand higher average wages to compensate for this effort, reducing firm profits.

Finally, we consider settings when principals manage teams of agents, and when there are different disclosure rules regarding contracts. We show that when KUJ effects are weak, private renegotiation increases distortions, but when KUJ effects are strong, equilibrium efficiency is enhanced if principals negotiate privately with individual agents. When contracts are disclosed externally to agents on other teams, effort is reduced and expected compensation increases. Consequently, when KUJ incentives are mild external disclosure increases firm profits in equilibrium. However, when KUJ incentives are strong incentives may collapse leading to lower profits.

Much remains for future research. Understanding the extent of peer sets, how they are determined, and how they may evolve over time is clearly important. While we have focused on peer effects between agents, in some setting peer effects between principals might also play a role. We have also assumed the strength of relative wealth concerns is known for each agent; agents may have
an incentive to exaggerate such preferences and obtain additional insurance in their wage contract if this were not the case.
8. Appendix

**Proof of Lemma 1:** Observe that \( \frac{\partial w_i}{\partial a_i} = x_i \) and

\[
\frac{\partial w_i}{\partial a_i} = \frac{1}{n} \sum_{j \neq i} \frac{\partial}{\partial a_i} (m_j + x_j q_j + y_j q_{-j})
= \frac{1}{n} \sum_{j \neq i} y_j n - \frac{1}{n} \sum_{k \neq j} \hat{q}_k / \hat{a}_i
= y_i
\]

(36)

Therefore, taking the wage contracts and actions of others as given, the agent will choose effort \( a_i \) to maximize his utility, which has the first order condition:

\[
\frac{\partial}{\partial a_i} E[U(w_i, a_i, w_{-i})] = E[u'(c_i)] \left( \frac{x_i - \delta y_i}{1 - \delta} - \frac{1}{k} a_i \right) = 0,
\]

where \( c_i \) is the agent’s adjusted consumption. Solving for \( a_i \) yields the result. ■

**Proof of Lemma 2:** Expected wages follow by direct calculation given the contract and production technology. The sensitivity \( \alpha_i \) to the agent’s own shock follows as in the previous lemma. The agent’s sensitivity to the average shock of others is given by

\[
(1 - \delta)^{-1} \left( n y_{i \text{ from } w_i} - \delta \left( x_j + (n-1)y_{j \text{ from } w_i} \right) \right) = \beta_i.
\]

The result then follows since the average idiosyncratic shock of others has \( 1/n \) times the variance of an individual idiosyncratic shock, and the total exposure to the common shock is \( \alpha_i + \beta_i \). ■

**Proof of Lemma 3:** To minimize

\[
\text{Var}(c_i) = \left[ \alpha_i^2 + \frac{1}{n} \beta_i^2 \right] (1 - \rho) + \left( \alpha_i + \beta_i \right)^2 \rho \sigma_c^2,
\]

we can solve for \( \beta_i \) from the first order condition

\[
\frac{2}{n} \beta_i (1 - \rho) + 2 \left( \alpha_i + \beta_i \right) \rho = 0
\]
verifying (13). Given the solution to \( \beta_i \), we have

\[
\text{Var}(c_i) = \alpha^2 \sigma_i^2 \left( 1 - \rho + \frac{1}{n} \left( \frac{\beta}{\alpha} \right)^2 (1-\rho) + \left( 1 + \frac{\beta}{\alpha} \right) \rho \right)
\]

\[
= \alpha^2 \sigma_i^2 \left( 1 - \rho + \frac{1}{n} \left( \frac{np}{1-\rho+np} \right)^2 (1-\rho) + \left( 1 + \frac{np}{1-\rho+np} \right) \rho \right)
\]

\[
= \alpha^2 \sigma_i^2 \left( 1 - \rho + \rho (1-\rho) \frac{np+(1-\rho)}{(1-\rho+np)^2} \right)
\]

\[
= \alpha^2 \sigma_i^2 \left( \frac{(1+np)(1-\rho)}{(1-\rho+np)} \right).
\]

\[\square\]

**Proof of Proposition 1:** The (IC) constraint is simply \( a_i = k\alpha_i \). Using the result of Lemma 3, we can choose \( \beta_i \) to minimize variance and thus the optimal contract maximizes

\[
k\alpha_i - \psi(k\alpha_i) - \lambda \alpha_i^2 \sigma_{n,\rho}^2
\]

The first order condition is

\[
k - k\alpha_i - 2\lambda \alpha_i \sigma_{n,\rho}^2 = 0.
\]

Hence the optimal solution is

\[
\alpha_i = \frac{1}{1 + 2\lambda k^{-1} \sigma_{n,\rho}^2},
\]

with \( \beta_i = -\alpha_i \theta_{n,\rho} \) from Lemma 3. From Lemma 1, \( a_i = k\alpha_i \). Given symmetry and the definitions in Lemma 2, \( \alpha_i = \alpha = \frac{x - \delta y}{1 - \delta} \) and so \( x = \alpha - \delta (\alpha - y) \). Finally, we have

\[
\beta_i = \beta = -\alpha \theta_{n,\rho} = \frac{(n-(n-1)\delta)y-\delta x}{1-\delta} = \frac{(n(1-\delta)+\delta)y-\delta (\alpha-\delta(\alpha-y))}{1-\delta}
\]

which we can solve for \( y \) as \( y = -\alpha \left( \frac{\theta_{n,\rho} - \delta}{n + \delta} \right) \). \[\square\]
**Proof of Corollary I.B:** First,

$$\text{Var}(w_i) = (x + ny)^2 \rho + (x^2 + ny^2)(1 - \rho),$$

where the first term captures $i$'s wage exposure to the common shock and the second term his exposure to idiosyncratic shocks. Using the solution from Proposition I we can calculate

$$\frac{\partial}{\partial \delta} (x + ny) = 0 \quad \text{and} \quad \frac{\partial}{\partial \delta} (x^2 + ny^2) = 2x'(x - y) < 0.$$

Next,

$$\text{Var}(w_i - w_{ij}) = \left(1 + \frac{1}{n}\right)(x - y)^2(1 - \rho)$$

which declines to zero by Corollary I.A. Finally,

$$\text{Cov}(w_i, w_j) = (x + ny)^2 \rho + (2xy + (n - 1)y^2)(1 - \rho)$$

which implies

$$\text{Corr}(w_i, w_j) = 1 - (x - y)^2(1 - \rho) / \text{Var}(w_i).$$

For $\delta = 0$: since at $\rho = 0.5$ $\text{Cov}(w_i, w_j) = -\frac{2 + n}{2(1 + n)^2} < 0$ and $\text{Cov}(w_i, w_j) = 0$ iff

$$\rho = -\frac{1}{n}, \text{or } \rho = 0, \text{or } \rho = 1, \quad \text{Cov}(w_i, w_j) \leq 0.$$

**Proof of Corollary I.C:** From (18), $\alpha$ is decreasing in $\lambda$, and from (19) this effect is the only impact on $x$ and $y$, implying the first result. Next, an increase in $\rho$ decreases $\sigma_{n,\rho}^2$, which raises $\alpha$ and effort. An increase in $\rho$ also increases $\theta_{n,\rho}$, and so $y / x$ declines because

$$y / x = \frac{-\left(\frac{\theta_{n,\rho} - \delta}{n + \delta}\right)}{1 - \delta\left(\frac{n + \theta_{n,\rho}}{n + \delta}\right)} = \frac{-\left(\frac{\theta_{n,\rho} - \delta}{n + \delta}\right)}{(1 - \delta)^{-\delta}\left(\frac{\theta_{n,\rho} - \delta}{n + \delta}\right)} = \frac{1}{\delta - \left(1 - \delta\right)(n + \delta)/\theta_{n,\rho} - \delta}.$$  

Taking a derivative of $y$ with respect to $\rho$, while letting $h = 2\lambda k^{-1}$ and simplifying yields
\[-\frac{n}{n+\delta}\left(1 + h - 2\delta x + h(\delta + n(1-\delta))x^2\right)\]
\[\frac{1}{h} + 1 - 2\delta x + (\delta + n(1-\delta))x^2\]}
which has the same sign as
\[-\left(1 - 2x + x^2\right) < 0.

The sign of the derivative of \(x\) with respect to \(\rho\) is the same as
\[-\delta(k + 2\lambda) + 4\left(n(1-\delta) + \delta\right)\lambda \rho - 2\left(\delta + n(1-\delta) - n^2(1-\delta)\right)\lambda \rho^2\] (37)

Note that at \(\rho = 0\) this expression is negative, and at \(\rho = 1\) it reduces to
\[2n(1+n)\lambda - (2n(1+n)\lambda + k)\delta\] (38)

Expression (38) is decreasing in \(\delta\) and equals zero at \(\delta = \frac{n^2 + n}{n^2 + n + k/(2\lambda)}\). So if
\[\delta < \frac{n^2 + n}{n^2 + n + k/(2\lambda)}\], then the relation between \(x\) and \(\rho\) is u-shaped. Otherwise, to be sure it is decreasing, we must make sure the maximum of (37) for \(\rho \in (0,1)\) is negative.

If the coefficient on \(\rho^2\) in (37) is non-negative, the result is clear. If the coefficient on \(\rho^2\) in (37) is negative, the maximum of (37) is obtained at \(\rho = \frac{\delta + n(1-\delta)}{\delta + n(1-\delta) - n^2(1-\delta)}\), which is larger than 1.

The sign of the derivative of \(ny/x\) with respect to \(n\) is the same as the sign of
\[-n^2(1-\delta)\rho - 2n(1-\delta)\delta \rho + \delta^2(1-\rho)\]
For \(\rho = 0\) this expression is positive, unless \(\delta = 0\). For \(\rho > 0\), it is evident that for \(n\) large enough this expression is negative, and that when equating this expression to zero and solving for \(n\) at least one of the solutions is negative. Comparing the value of \(ny/x\) for \(n = 2\) to the value for \(n = 1\) yields after some algebra that it is larger at \(n = 2\) iff \(\rho < \frac{\delta^2}{\delta + 2(1-\delta^2)}\).

The change in effort as \(n\) increases follows since effort is second-best, and if \(\rho > 0\), then aggregate peer output becomes a more informative signal.
**Proof of Proposition II:** We begin by verifying the result in the context of Proposition I. The case for $x$ is immediate. For $y$, note that

\[ ny = (1-\delta)ny_0 + \delta(x + (n-1)y) \]
\[ \Leftrightarrow (1-\delta)ny = (1-\delta)ny_0 + \delta(x - y) \]
\[ \Leftrightarrow ny = ny_0 + \delta(x - y) / (1-\delta) = ny_0 + \delta(\alpha - y) = -\alpha \left( \frac{\theta_{n,p} - \delta n + \theta_{n,p}}{n + \delta} \right) = -n\alpha \left( \frac{\theta_{n,p} - \delta}{n + \delta} \right). \]

To understand the more general result, note that (20) implies that given contract $w_i$, agent $i$’s relative wage is equal to $w_{0i}$. Thus, agents’ incentives with contracts $w_i$ and $\delta_i > 0$ are identical to their incentives with contracts $w_{0i}$ and $\delta_i = 0$. Moreover, summing (20) over all agents and using the fact that $\sum_i w_i = \sum_i w_{-i}$, we see that aggregate wage bill is unchanged. Thus, the principal can provide the same incentives at the same cost for any $\delta$. ■

**Proof of Proposition III:** Applying (22) we have

\[ x = (1-\delta)x_0 + \delta \left( \frac{z}{n} y_0 + \frac{n-z}{n} y \right) \]
\[ y = (1-\delta)y_0 + \delta \left( \frac{z}{n} y_0 + \frac{n-z-1}{n} y + \frac{1}{n} x \right) \]
\[ \hat{y} = (1-\delta)y_0 + \delta \left( \frac{z-1}{n} y_0 + \frac{1}{n} x_0 + \frac{n-z}{n} \hat{y} \right) \]

which we can solve to derive (23). Note that from (23),

\[ x - y_0 = \left[ \frac{(1-\delta)n}{n + \delta} \left( \frac{\delta + (1-\delta)n + \delta z}{(1-\delta)n + \delta z} \right) \right] (x_0 - y_0), \]

which implies $x < x_0$ and $x$ declines with $z$. The results for $y$ and $\hat{y}$ are immediate. ■

**Proof of Corollary III.A:**

We first verify that $x > 0$. From before, $x$ declines with $z$, so it is sufficient to consider $z = n$. From (40), when $z = n$, $x = y_0 + (1-\delta)(x_0 - y_0)$. Using the definitions of $x_0$ and $y_0$ (see Proposition III), we see that $x$ is positive if $\delta < n / (n + \theta_{n,p})$. Next, note that
\[ \frac{y}{x} = \frac{y}{y + \frac{n(1-\delta)(x_0 - y_0)}{n+\delta}} \]

which in the region \( x > 0 \) decreases with \( z \) because \( y \) decreases with \( z \).

The sign of the derivative of \( \dot{y} / x \) with respect to \( z \) is proportional to

\[ -\left(y_0\delta + n\left(x_0(1-\delta) - y_0(1-2\delta)\right)\right), \]

which is negative when

\[ \delta \leq \frac{n + \theta_{n,\rho}}{n + \left(2 + \frac{1}{n}\right)\theta_{n,\rho}} < \frac{n}{n + \theta_{n,\rho}} \]

Where the second inequality follows because \( \theta_{n,\rho} < 1 \). Finally, for \( \ddot{y} / x \) the result follows by direct calculation of the derivative. ■

**Proof of Proposition IV:** Let \( G_i \) be agent \( i \)'s subgroup. By the same logic as **Proposition II**, the optimal contract satisfies

\[ w_i = (1-\delta)w_{0i} + \delta\hat{w}_{-i}, \quad (41) \]

where \( \hat{w}_{-i} = \frac{1}{n}\sum_{j\in G_i\setminus\{i\}} w_j \). The result then follows by the same calculations as in the proof of **Proposition III**. The comparative statics for \( y / x \) follow from direct calculation. ■

**Proof of Proposition V:** Substituting \( \alpha_i = k\alpha_i \) from the (IC) constraint, using the result of **Lemma 3** to set \( \beta_i^n = -\alpha_i^n\theta_{n,\rho} \) to minimize variance, and finally using the fact that \( \partial w_{-i} / \partial a_i = y_{-i} \) from (36), the optimization in (28) is equivalent to

\[ \max_{\alpha_i} k\alpha_i - \delta y_{-i}(k\alpha_i) - (1-\delta)\left(\psi(k\alpha_i) + \lambda\alpha_i^2\sigma_{n,\rho}^2\right) \]

The first order condition is

\[ (1-\delta y_{-i})k - (1-\delta)\left(k\alpha_i + 2\lambda\alpha_i\sigma_{n,\rho}^2\right) = 0, \]

and so the optimal solution is

40
\[
\alpha'^m = \frac{1 - \delta y_{ij}}{1 - \delta} \frac{1}{1 + 2\lambda k^{-1} \sigma_{n,\rho}^2} = \frac{1 - \delta y_{ij}}{1 - \delta} \alpha'^s.
\]

Imposing symmetry (which we show in **Lemma A.1** is the unique equilibrium), we know that the mapping from \((\alpha'^m, \beta'^m)\) to \((x'^m, y'^m, a'^m)\) is unchanged from the single principal case. Thus,

\[
y'^m = -\alpha'^m \left( \frac{\theta_{n,\rho} - \delta}{n + \delta} \right) = -\left( 1 - \delta y'^m \right) \frac{\theta_{n,\rho} - \delta}{n + \delta} = \left( 1 - \delta y'^m \right) \alpha'^s.
\]

We can solve for \(y'^m\) as

\[
y'^m = \frac{1}{1 - \delta(1 - y'^s)} y'^s,
\]

and it is easy to see that this same scaling factor will apply to each of the contract variables. Next, because \(\alpha'^s < 1\) and \(\theta_{n,\rho} [0,1]\), we have

\[
1 > y'^s = -\alpha'^s \left( \frac{\theta_{n,\rho} - \delta}{n + \delta} \right) > -\frac{1 - \delta}{n + \delta} > -\frac{1 - \delta}{\delta},
\]

so that the scaling factor exceeds 1 for \(\delta > 0\). For the comparative statics with respect to \(\delta\), note that

\[
\delta(1 - y'^s) = \delta \left( 1 + \alpha'^s \left( \frac{\theta_{n,\rho} - \delta}{n + \delta} \right) \right) = \delta \left( 1 + \alpha'^s \left( -1 + \frac{n + \theta_{n,\rho}}{n + \delta} \right) \right)
\]

\[
= \delta (1 - \alpha'^s) + \alpha'^s \left( n + \theta_{n,\rho} \right) \left( \frac{\delta}{n + \delta} \right)
\]

which is strictly increasing in \(\delta\). Finally, because \(E[w_i] = E[w_{-i}]\) in equilibrium, aggregate welfare is as in (17), and so declines as \(\alpha'^m\) departs from \(\alpha'^s\). 

**Proof of Corollary V.B:** Apart for sensitivity of \(x\) with respect to \(\rho\) and sensitivity of effort with respect to \(n\), results follow immediately from taking derivatives of expressions in **Proposition V**.

The sign of the derivative of \(x\) with respect to \(\rho\) is the same as the sign of
\((n-1)n(1-\delta) - \delta\) \(\rho^2 + 2(n(1-\delta)+\delta)\rho - \delta\)

Since this expression is quadratic in \(\rho\), is negative at \(\rho = 0\) and positive at \(\rho = 1\), the result follows.

The sign of the derivative of effort with respect to \(n\) is the same as the sign of

\[-n^2(1-\delta)(k\delta - 2\lambda(1-\rho))\rho^2 + 2n\delta(1-\rho)\rho(k\delta + 2(1-\delta)\lambda\rho) + \delta^2(1-\rho)(k + 2(1-\delta)\lambda\rho^2)\]

This expression is quadratic in \(n\), is zero at \(\rho = \delta = 0\), positive when \(\rho = 0\) and \(\delta > 0\) or \(\frac{k}{2\lambda} \leq \frac{1-\rho}{\delta}\)
. When \(\frac{k}{2\lambda} > \frac{1-\rho}{\delta}\) the \(n^2\) term is negative, and directly comparing effort levels at \(n = 1\) and \(n = 2\) yields the condition as to when the sensitivity with respect to \(n\) is tent shaped or decreasing. ■

**Proof of Proposition VI:** Let \(w_i\) be the wage paid to a member of the principal’s team, and \(w_{-i}\) the average wage of a non-member. Then, because the fraction \(\hat{n}/n\) of the agent’s peers are on the same team, the participation constraint (27) becomes

\[E[w_i] = \hat{n} \delta E[w_i] + (1-\hat{n}) \delta E[w_{-i}] + (1-\delta) [c_0 + \psi(a_i) + \lambda Var(c_i)]\]

\[E[w_i] = \frac{n\delta - \hat{n}\delta}{n - \hat{n}\delta} E[w_{-i}] + \frac{n - n\delta}{n - \hat{n}\delta} [c_0 + \psi(a_i) + \lambda Var(c_i)]\]

\[E[w_i] = \hat{\delta} E[w_{-i}] + (1-\hat{\delta}) [c_0 + \psi(a_i) + \lambda Var(c_i)]\]

Equation (30) then follows exactly as in the proof of Proposition V. Because

\[\hat{\delta}(1-y^*) = \frac{n - \hat{n}}{n - \hat{n}\delta} \times \delta(1-y^*),\]

and both terms are increasing with \(\delta\) (the latter from (43)), effort increases with \(\delta\) if \(\hat{n} < n\).

Because \(\hat{\delta}\) is decreasing in \(\hat{n}\), the distortion declines with team size. ■

**Proof of Proposition VII:** Each principal has a potential incentive to contract privately with one agent so as to reduce the wage paid to the \(\hat{n}\) other agents under his span of control. Thus, the principal’s problem when considering such a deviation changes from (28) to include this benefit:

\[
\max_{(x, y, a_i)} a_i - \left( (\hat{n} + \delta) E[w_{-i}] + (1-\delta) \left[ \psi(a_i) + \lambda Var(c_i) \right] \right) \quad s.t. \ (IC) \quad (44)
\]

Following the same solution method as in Proposition V, at the optimum we have
\[ y^m = \left( \frac{1 - (\hat{n} + \delta) y^p}{1 - \delta} \right) y^s. \]

We can solve for \( y^p \) as

\[ y^p = \frac{1}{1 - \delta(1 - y^s) + \hat{n} y^s} y^s, \]

and again this same scaling factor will apply to each of the contract variables. Next, because \( \alpha^* < 1 \) and \( \theta_{n,p} \in [0,1] \), we have

\[ \frac{\delta}{\hat{n} + \delta} \geq \frac{\delta}{n + \delta} > y^s = -\alpha^* \left( \frac{\theta_{n,p} - \delta}{n + \delta} \right) > -\frac{1 - \delta}{n + \delta} \geq -\frac{1 - \delta}{\hat{n} + \delta}, \]

so that the scaling factor exceeds 1 for all \( \delta \). For the comparative statics with respect to \( \delta \), note that

\[ \delta(1 - y^s) - \hat{n} y^s = \delta - (n + \delta) y^s + (n - \hat{n}) y^s \]
\[ = \delta - (n + \delta) \left( -\alpha^* \left( \frac{\theta_{n,p} - \delta}{n + \delta} \right) \right) + (n - \hat{n}) y^s \]
\[ = \delta + \alpha^* \left( \theta_{n,p} - \delta \right) + (n - \hat{n}) y^s \]
\[ = (1 - \alpha^*) \delta + \alpha^* \theta_{n,p} + (n - \hat{n}) y^s \]

is strictly increasing in \( \delta \). The comparative statics with respect to \( \hat{n} \) follow since \( y^s < \) \((>)0\) iff \( \delta < \) \((>)\theta_{n,p} \). Finally, the special case of \( \hat{n} = n \) is implied by (46). ■

**Proof of Proposition VIII:** Because in all cases effort weakly exceeds the optimum from **Proposition I**, the more efficient outcome will be the one that leads to the lowest effort level. To compare effort levels, we need only to compare the scale factors in (30) and (31). Thus, public contracting dominates private contracting if and only if

\[ 1 - \hat{n}(1 - y^s) > 1 - \delta(1 - y^s) + \hat{n} y^s. \]

We can rewrite this as

\[ \hat{n} y^s < \frac{\hat{n} - \hat{n} \delta}{n - \hat{n} \delta} \delta(1 - y^s), \]

43
or more simply

\[ y' < \frac{(1-\delta)\delta}{n-n\delta}(1-y'). \] (47)

Recall that \( y' = -\alpha' \left( \frac{\theta_{n,\rho} - \delta}{n + \delta} \right) \) and \( \theta_{n,\rho} \in (0,1) \). Hence \( y' < 0 \) for \( \delta = 0 \) and \( y' > 0 \) for \( \delta = 1 \).

The result then follows since the right-hand side of (47) converges to zero for \( \delta = 0 \) or 1. ■

**Proof of Proposition IX:** We can calculate

\[
\frac{\partial}{\partial a_i} \left( a_i - \delta E[w_{-i}] - (1-\delta)\psi(a_i) \right) = 1 - \delta y_j - (x_i - \delta y_j) = 1 - x_i
\] (48)

Then, using the (IC) constraint for \( a_i \) and the expression for \( \text{Var}(c_i) \), we have the following first order conditions (which are sufficient given the strict concavity of the objective function) for the optimal choice of \((x_i, y_i)\) given \((x_j, y_j)\):

\[
(1-x_i) - 2\lambda k^{-1} \left[ (1-\rho)(x_i - \delta y_j) + \rho(x_i - \delta x_j + n y_i - \delta y_j) \right] = 0
\] (49)

\[
\left( \frac{\delta}{n} \right)^2 \left( x_i + (n-1)y_j \right)
\]

\[
-2\lambda k^{-1} \left[ \frac{1}{n} \right] \left( n y_i - \delta x_j - (n-1)\delta y_j \right) + \rho(x_i - \delta x_j + n y_i - \delta y_j) \right] = 0
\] (50)

The first order conditions above are identical to the first order conditions for the optimal contract in Proposition V with the exception of the first term in (50). This term arises because of the effect of \( y_i \) on the effort choice \( a_j \) of other agents, which impacts their expected wage:

\[ E[w_{-i}] = E[w_i] = m_j + x_j a_j + y_j \left( a_i + (n-1)a_j \right) \]

It is this term that implies that \( \beta_i \) (which is determined by \( y_i \)) will not be chosen as the optimal hedge to minimize the variance of \( c_i \), but instead will be distorted to impact others’ effort.

Solving (49) and (50) for \((x_i, y_i)\), we find the following “reaction functions”: 44
\[ x_i = \alpha_s + \delta y_j \left(1 - \alpha_s\right) - (x_j + (n-1)y_j) \frac{\delta^2}{n} \alpha_s \theta_{n,o} \]  \hspace{1cm} (51)\\

\[ ny_i = \left(x_j + (n-1)y_j\right) \left(\delta + \frac{\delta^2}{n} \left(1 - \alpha_s \theta_{n,o} \rho\right) \alpha_s \theta_{n,o} \right) - (1 - \delta y_j) \alpha_s \theta_{n,o} \]  \hspace{1cm} (52)

These reaction functions are equivalent to the reaction functions in the setting of Proposition V upon replacing the \( \delta^2 \) terms with zeros. Finally, we solve for a symmetric equilibrium by solving (51) and (52) with \((x_i, y_i) = (x_j, y_j)\). After much tedious algebra one can solve for

\[ x^{md} = x^m + \frac{\delta^2 (1 - \delta \rho) \left(1 + (n-1)\rho\right) (\delta - \theta_{n,o})}{W_i(W_1 + W_2)} \]  \hspace{1cm} (53)\\

\[ y^{md} = y^m + \frac{\delta^2 (1 - \delta \rho) \left(1 - \delta \rho + \frac{1}{2\lambda k^{-1}}\right)}{W_i(W_1 + W_2)} \]  \hspace{1cm} (54)

We show in Lemma A.2 that the equilibrium must be symmetric. \(\blacksquare\)

**Lemma A.1:** With multiple principal-agent pairs and private contracting the equilibrium is unique.

**Proof:**

\[ w_{-i} = m_{-i} + \frac{1}{n} \sum_{j \neq i} x_j q_j + y_{-i} q_i + \frac{n-1}{n} \sum_{j \neq i} y_{-(i,j)} q_j \]  \hspace{1cm} (55)

where

\[ y_{-(i,j)} \equiv \frac{1}{n-1} \sum_{k \neq i,j} y_k \]  \hspace{1cm} (56)

Implies that

\[ w_{i} - \delta w_{-i} = m_{i} - \delta m_{-i} + (x_{i} - \delta y_{-i}) q_{i} + \frac{1}{n} \sum_{j \neq i} \left(\delta y_{j} - \delta \left(x_{j} + (n-1)y_{-(i,j)}\right)\right) q_{j} \]  \hspace{1cm} (57)

\[ Var[c_i] = \frac{1}{(1 - \delta)^2} \text{Var}[w_i - \delta w_{-i}] \]

where
\[
\begin{align*}
\text{Var}[w_i - \delta w_{-i}] &= (x_i - \delta y_i)^2 + 2(x_i - \delta y_i)\left(y_i - \delta(x_i + (n-1)y_{-(i,j)})\right) + \frac{1}{n^2} \sum_{j \neq i} \sum_{k \neq i, j} \left(y_i - \delta(x_j + (n-1)y_{-(i,j)})\right)\left(y_i - \delta(x_k + (n-1)y_{-(i,k)})\right) \\
&+ \frac{1}{n^2} \sum_{j \neq i} \left(y_i - \delta(x_j + (n-1)y_{-(i,j)})\right)^2
\end{align*}
\]

(58)

Using the above expressions, the optimal solution of optimization (28) is obtained by imposing \(IC_i\) and taking first order conditions for the optimal choice of \((x_i, y_i)\) given \(\{(x_j, y_j)\}_{j \neq i}\).

After rearranging the first order conditions we find the following “reaction functions”
\[
\begin{align*}
x_i &= \alpha' + \frac{\delta}{n}(1 - \alpha')ny_i \\
y_i &= \alpha'\theta_{n,p} + \delta x_i - \frac{\delta}{n}(n - 1 - \alpha'\theta_{n,p})(y_i - y_i)
\end{align*}
\]

(59)

Taking the difference between the reaction functions of principals \(i\) and \(k\), and rearranging each of the two differences yields
\[
\begin{align*}
x_k - x_i &= -\frac{\delta}{n}(1 - \alpha')(y_k - y_i) \\
-(y_k - y_i) &= \frac{\delta}{n}(x_k - x_i) + \frac{\delta}{n}(n - 1 - \alpha'\theta_{n,p})(y_k - y_i)
\end{align*}
\]

(60)

Plugging the first equation into the second and rearranging yields
\[
0 = \left[\frac{-\delta^2}{n^2}(1 - \alpha') + \frac{\delta}{n}(n - 1 - \alpha'\theta_{n,p}) + n\right](y_k - y_i)
\]

(61)

Note that for \(n > 1\) clearly \(\left[\right] > 0\).

For \(n = 1\):
\[
\left[\right] = -\delta^2(1 - \alpha') - \delta\alpha'\theta_{n,p} + 1 = -\delta^2(1 - \alpha' + \alpha'\theta_{n,p}) + 1 > -\delta^2 + 1 > 0
\]

Finally, \(\left[\right] > 0\) implies that \(y_k = y_i\) which from the first equation implies \(x_k = x_i\) as well. ■

**Lemma A.2:** Suppose independent principals each manage a single agent, and all contracts are disclosed prior to agents choosing effort. Then the equilibrium must be symmetric.
PROOF: Allowing contract to potentially differ across principals, and following a similar derivation toLemma A.1, the “reaction functions” corresponding to Equations (51) and (52) take the form

\[ x_i = \alpha_s + \delta y_{-i} (1 - \alpha_s) - (x_i + (n-1)y_{-i}) \frac{\delta^2}{n^2} \alpha_s \theta_{n,p} \]  
\[ ny_i = (x_{-i} + (n-1)y_{-i}) \left( \delta + \frac{\delta^2}{n^2} \frac{1 - \alpha_s \theta_{n,p} \rho}{1 - \alpha_s} \frac{\alpha_s \theta_{n,p}}{\rho} \right) - (1 - \delta y_{-i}) \alpha_s \theta_{n,p} \]

Taking the difference between the reaction functions of principals \( i \) and \( k \), and rearranging each of the two differences yields

\[ (x_k - x_i) \left( \frac{1}{n} \frac{\delta^2}{n} \alpha_s \theta_{n,p} - 1 \right) = (y_k - y_i) \left( \frac{\delta}{n} (1 - \alpha_s) - \frac{n-1}{n} \frac{\delta^2}{n^2} \alpha_s \theta_{n,p} \right) \]

\[ -n (y_k - y_i) = \left( (x_k - x_i) + (n-1)(y_k - y_i) \right) \frac{1}{n} \left( \delta + \frac{\delta^2}{n^2} \frac{1 - \alpha_s \theta_{n,p} \rho}{1 - \alpha_s} \frac{\alpha_s \theta_{n,p}}{\rho} \right) + \frac{\delta}{n} (y_k - y_i) \alpha_s \theta_{n,p} \]

Using the first equation to plug into the second and then simplifying yields

\[ 0 = \left[ \left( \frac{\delta}{n} (1 - \alpha_s) - (n-1) \right) \frac{1}{n} \left( \delta + \frac{\delta^2}{n^2} \frac{1 - \alpha_s \theta_{n,p} \rho}{1 - \alpha_s} \frac{\alpha_s \theta_{n,p}}{\rho} \right) + \frac{\delta}{n} \alpha_s \theta_{n,p} + n \right] (y_k - y_i) \]

Note that for \( n > 1 \) clearly \([ ] > 0\).

For \( n = 1 \), \( \theta_{n,p} = \rho \) and

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\[
\begin{align*}
[ & ] &= -\delta (1-\alpha_s) \\
& & \left(1 - \delta^2 \alpha_s \theta_{n,p} \right) \left( \delta + \delta^2 \left( \frac{1-\alpha_s \theta_{n,p}}{1-\alpha_s} \right) \frac{\alpha_s \theta_{n,p}}{\rho} \right) + \delta \alpha_s \theta_{n,p} + 1 \\
& = -\delta^2 (1-\alpha_s) - \delta^3 (1-\alpha_s \rho^2) \alpha_s + (1-\delta^2 \alpha_s \rho) (\delta \alpha_s \rho + 1) \\
& = \frac{(1-\delta) (1+\delta (1+\alpha_s (\delta + \rho)))}{(1-\delta^2 \alpha_s \rho)} > 0
\end{align*}
\]

Finally, \([ ] > 0\) implies that \(y_k = y_i\) which from the first equation implies also that \(x_k = x_i\). ■

9. References


